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KAGARLIS, Marios

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## U.S. PATENT DOCUMENTS

*EXAMINER INITIAL	DOCUMENT NUMBER	DATE	NAME	CLASS	SUBCLASS	FILING DATE IF APPROPRIATE
<i>MJ</i>	2002/062207 A1	05/23/2002	Faghr'i	—	—	

## FOREIGN PATENT DOCUMENTS

DOCUMENT	DATE	COUNTRY	CLASS	SUBCLASS	TRANSLATION YES NO

## OTHER DOCUMENTS (including Author, Title, Date, Pertinent pages, etc.)

<i>MJ</i>	R. HOSOI et al., "Dynamical model of a pedestrian in a crowd", Robot and Human Communication, 5 <sup>th</sup> IEEE International Workshop on Tsukuba, November 11, 1996, Pgs. 44-49, XP010212810
<i>MJ</i>	D. HELBING et al., "Social force model for pedestrian dynamics", Phys. Rev. E, Stat, Phys, Plasmas Fluids Relat. Interdiscip. Top., Physical Review E (Statistical Physics, Plasmas, Fluids, and Related Interdisciplinary Topics), May 1995, Vol. 51, No. 5, Pt. A, May 1995, Pgs. 4282-4286, XP002277054
<i>MJ</i>	S. GOLDSTEIN et al., "Scalable dynamical systems for multi-agent steering and simulation", Proceedings of the 2001 IEEE International Conference on Robotics and Automation., Proceedings of the IEEE International Conference on Robotics and Automation, Vol. 1 of 4, May 21, 2001, Pgs. 3973-3980, XP010550757

\*Examiner

Date Considered

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